

OPTIMIZATIONS ON TOTALLY REAL SUBMANIFOLDS OF LCS-MANIFOLDS USING CASORATI CURVATURES

MOHAMMAD HASAN SHAHID AND ALIYA NAAZ SIDDIQUI

ABSTRACT. In the present paper, we derive two optimal inequalities for totally real submanifolds and C -totally real submanifolds of LCS-manifolds with respect to Levi-Civita connection and quarter symmetric metric connection by using T. Oprea's optimization method.

1. Introduction

The concept of Lorentzian concircular structure manifold (LCS-manifolds) is studied by A. A. Shaikh as a generalization of LP-Sasakian manifolds in [18]. These manifolds are of great interest in the general theory of relativity and cosmology [19, 20]. Many researchers have studied LCS-manifolds (for example [1, 8–11, 21]).

The notion of semi-symmetric linear connection on smooth manifolds is initiated by Friedmann and Schouten in [4]. Later on, Golab has introduced the idea of quarter symmetric linear connection on such smooth manifolds as a generalization of semi-symmetric connection in [6].

In 1890, F. Casorati [2] has defined Casorati curvature and used it at the place of traditional Gauss curvature. The geometrical importance of the Casorati curvatures has been discussed by many researchers [3, 7, 12, 25]. Due to its vast geometric significance it drew attention of researchers to construct optimal inequalities for Casorati curvatures for different set ups [5, 13, 14, 22–24, 26, 27].

The outline of the present paper is as follows: Section 2 is preliminary in nature. Section 3 deals with the study of Casorati curvatures. Section 4 derives the optimal inequalities for totally real submanifolds and C -totally real submanifolds of LCS-manifolds with respect to Levi-Civita connection. Section 5 gives the proof of the geometric inequalities for totally real submanifolds and C -totally real submanifolds of LCS-manifolds with respect to quarter symmetric metric connection.

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2. LCS-manifolds and their submanifolds

Definition ([16, 18]). A Lorentzian manifold \overline{M} together with the unit time-like concircular vector field ξ , its associated 1-form η and an $(1, 1)$ tensor field φ is said to be a Lorentzian concircular structure manifold (or LCS-manifold).

In an n -dimensional $(LCS)_n$ -manifold \overline{M} , $n > 2$, the following relations hold [18]:

$$\begin{aligned} (1) \quad & \eta(\xi) = -1, \quad \varphi(\xi) = 0, \quad \eta \circ \varphi = 0, \\ (2) \quad & g(\varphi X, \varphi Y) = g(X, Y) + \eta(X)\eta(Y), \quad \varphi^2 X = X + \eta(X)\xi, \\ (3) \quad & \overline{R}(X, Y)Z = \varphi \overline{R}(X, Y)Z + (\alpha^2 - \rho) \left[g(Y, Z)\eta(X) - g(X, Z)\eta(Y) \right] \xi \end{aligned}$$

for any $X, Y, Z \in \Gamma(T\overline{M})$.

We consider $\overline{\nabla}$ is the operator of covariant differentiation with respect to the Lorentzian metric g and α is a non-zero scalar function satisfying the following:

$$(4) \quad \overline{\nabla}_X \alpha = (X\alpha) = d\alpha(X) = \rho\eta(X)$$

for any $X \in \Gamma(T\overline{M})$, where ρ is a certain scalar function given by

$$(5) \quad \rho = -(\xi\alpha).$$

Also,

$$\begin{aligned} (6) \quad \overline{R}(X, Y, Z, W) = & \overline{R}(X, Y, Z, \varphi W) + (\alpha^2 - \rho) \left[g(Y, Z)\eta(X) \right. \\ & \left. - g(X, Z)\eta(Y) \right] \eta(W) \end{aligned}$$

for any $X, Y, Z, W \in \Gamma(T\overline{M})$.

Remark 2.1. If we assume that $\alpha = 1$, then Lorentzian concircular structure becomes LP-Sasakian structure [15].

Let M be an m -dimensional submanifold of an n -dimensional manifold \overline{M} with induced metric g . The Gauss equation is given by [29]

$$(7) \quad \begin{aligned} \overline{R}(X, Y, Z, W) = & R(X, Y, Z, W) + g(\zeta(X, Z), \zeta(Y, W)) \\ & - g(\zeta(X, W), \zeta(Y, Z)) \end{aligned}$$

for any $X, Y, Z, W \in \Gamma(TM)$. Here ζ is the second fundamental form of M in \overline{M} .

Definition ([6]). A linear connection $\hat{\nabla}$ in an n -dimensional smooth manifold \overline{M} is said to be a quarter symmetric connection if its torsion tensor T is of the form

$$T(X, Y) = \hat{\nabla}_X Y - \hat{\nabla}_Y X - [X, Y] = \eta(Y)\varphi X - \eta(X)\varphi Y,$$

where η is an 1-form and φ is a tensor of type $(1, 1)$.

Remark 2.2. If we assume that $\varphi X = X$, then the quarter symmetric connection reduces to semi-symmetric connection.

Definition ([6]). The quarter symmetric connection $\hat{\nabla}$ is said to be a quarter symmetric metric connection if $\hat{\nabla}$ satisfies the following condition:

$$(\hat{\nabla}_X g)(Y, Z) = 0$$

for any $X, Y, Z, W \in \Gamma(T\bar{M})$.

The relation between quarter symmetric metric connection $\hat{\nabla}$ and Riemannian connection $\bar{\nabla}$ on a $(LCS)_n$ -manifold \bar{M} is given by [11]

$$\hat{\nabla}_X Y = \bar{\nabla}_X Y + \eta(Y)\varphi X - g(\varphi X, Y)\xi.$$

If \hat{R} and \bar{R} are the curvature tensors of a $(LCS)_n$ -manifold \bar{M} with respect to quarter symmetric metric connection $\hat{\nabla}$ and Riemannian connection $\bar{\nabla}$, then [10]

$$\begin{aligned} \hat{R}(X, Y, Z, W) = & \bar{R}(X, Y, Z, W) + (2\alpha - 1) \left[g(\varphi X, Z)g(\varphi Y, W) \right. \\ & \left. - g(\varphi Y, Z)g(\varphi X, W) \right] + \alpha \left[\eta(Y)g(X, W) \right. \\ & \left. - \eta(X)g(Y, W) \right] \eta(Z) + \alpha \left[g(Y, Z)\eta(X) \right. \\ & \left. - g(X, Z)\eta(Y) \right] \eta(W) \end{aligned} \quad (8)$$

for any $X, Y, Z, W \in \Gamma(TM)$.

Let M be an m -dimensional submanifold of an n -dimensional $(LCS)_n$ -manifold \bar{M} with respect to quarter symmetric metric connection $\hat{\nabla}$ and $\hat{\nabla}$ be the induced connection of M associated to the quarter symmetric metric connection. Also let $\hat{\zeta}$ be the second fundamental form of M with respect to $\hat{\nabla}$. Then the relation (7) becomes

$$\begin{aligned} \hat{R}(X, Y, Z, W) = & \hat{R}(X, Y, Z, W) + g(\hat{\zeta}(X, Z), \hat{\zeta}(Y, W)) \\ & - g(\hat{\zeta}(X, W), \hat{\zeta}(Y, Z)) \end{aligned} \quad (9)$$

for any $X, Y, Z, W \in \Gamma(TM)$. Here \hat{R} is the curvature tensor of M with respect to the induced connection associated to the quarter symmetric metric connection.

Definition ([28, 29]). (i) A submanifold M of a contact metric manifold \bar{M} is said to be anti-invariant if for any X tangent to M , φX is normal to M , i.e., $\varphi(TM) \subset T^\perp M$ at every point of M , where $T^\perp M$ denotes the normal bundle of M .

(ii) A submanifold M in a contact metric manifold \bar{M} is called a C -totally real submanifold in \bar{M} if every tangent vector of M belongs to the contact distribution.

Remark 2.3. We note that if a submanifold M of a contact metric manifold \bar{M} is normal to the structure vector field ξ , then it is anti-invariant. Also, a submanifold M in a contact metric manifold \bar{M} is a C -totally real submanifold if the structure vector field ξ is normal to M . Therefore it is clear that C -totally real submanifolds in a contact metric manifold are anti-invariant, as they are normal to ξ .

For a totally real submanifold and a C -totally real submanifold of a $(LCS)_n$ -manifold \bar{M} , $\hat{\zeta}$ is given by [10]

$$(10) \quad \hat{\zeta}(X, Y) = \zeta(X, Y) + \eta(Y)\varphi X$$

and

$$(11) \quad \hat{\zeta}(X, Y) = \zeta(X, Y),$$

respectively, for any $X, Y \in \Gamma(TM)$.

3. Casorati curvatures

Let \bar{M} be an n -dimensional $(LCS)_n$ -manifold and M be an m -dimensional submanifold in \bar{M} . Let $\{\mathcal{E}_1, \dots, \mathcal{E}_m\}$ be an orthonormal basis of $T_\varphi M$ and $\{\mathcal{E}_{m+1}, \dots, \mathcal{E}_n\}$ be an orthonormal basis of $T_\varphi^\perp M$ at any $\varphi \in M$. Then the scalar curvature $\sigma(\varphi)$ at φ is given by

$$(12) \quad \sigma(\varphi) = \sum_{1 \leq i < j \leq m} K(\mathcal{E}_i \wedge \mathcal{E}_j)$$

and the normalized scalar curvature ϱ is given by

$$(13) \quad \varrho = \frac{2\sigma}{m(m-1)},$$

where $K(\Lambda)$ denotes the sectional curvature of the plane section $\Lambda \subset T_\varphi M$.

The mean curvature vector \mathcal{H} is defined as

$$(14) \quad \mathcal{H} = \frac{1}{m} \sum_{i,j=1}^m \zeta(\mathcal{E}_i, \mathcal{E}_j)$$

and the squared norm of mean curvature is given by

$$(15) \quad \|\mathcal{H}\|^2 = \frac{1}{m^2} \sum_{a=m+1}^n \left(\sum_{i=1}^m \zeta_{ii}^a \right)^2.$$

We also put

$$\zeta_{ij}^a = g(\zeta(\mathcal{E}_i, \mathcal{E}_j), \mathcal{E}_a), \quad i, j \in \{1, 2, \dots, m\}, \quad a \in \{m+1, m+2, \dots, n\}.$$

The Casorati curvature \mathcal{C} of M is defined by

$$(16) \quad \mathcal{C} = \frac{1}{m} \sum_{a=m+1}^n \sum_{i,j=1}^m (c_{ij}^a)^2.$$

Let us assume an r -dimensional subspace Ψ of TM , $r \geq 2$, whose orthonormal basis is $\{\mathcal{E}_1, \mathcal{E}_2, \dots, \mathcal{E}_r\}$. Then we have

$$(17) \quad \sigma(\Psi) = \sum_{1 \leq \alpha < \beta \leq r} K(\mathcal{E}_\alpha \wedge \mathcal{E}_\beta)$$

and

$$(18) \quad \mathcal{C}(\Psi) = \frac{1}{r} \sum_{a=m+1}^n \sum_{i,j=1}^m (c_{ij}^a)^2,$$

where $\sigma(\Psi)$ and $\mathcal{C}(\Psi)$ are the scalar curvature and Casorati curvature of Ψ , respectively.

The following δ -Casorati curvatures $\delta_{\mathcal{C}}(m-1)$ and $\widehat{\delta}_{\mathcal{C}}(m-1)$

$$(19) \quad [\delta_{\mathcal{C}}(m-1)]_{\wp} = \frac{1}{2} \mathcal{C}_{\wp} + \frac{m+1}{2m} \inf\{\mathcal{C}(\Psi) | \Psi : \text{a hyperplane of } T_{\wp}M\}$$

and

$$(20) \quad [\widehat{\delta}_{\mathcal{C}}(m-1)]_{\wp} = 2\mathcal{C}_{\wp} + \frac{2m-1}{2m} \sup\{\mathcal{C}(\Psi) | \Psi : \text{a hyperplane of } T_{\wp}M\}$$

are known as the normalized δ -Casorati curvatures.

Definition ([14]). A point $p \in M$ is said to be an invariantly quasi-umbilical point if there exist $n-m$ orthogonal unit normal vector $\{\mathcal{E}_{m+1}, \dots, \mathcal{E}_n\}$ such that the shape operator with respect to all directions \mathcal{E}_r have an eigenvalue of multiplicity $m-1$ and that for each \mathcal{E}_r the distinguished eigendirection is the same. The submanifold M is said to be an invariantly quasi-umbilical submanifold if each of its point is an invariantly quasi-umbilical point.

For the main results, we need following lemma:

Lemma 3.1 ([17]). *Let M be a Riemannian submanifold of Riemannian manifold $(\overline{M}, \overline{g})$, where g is the induced metric on M from \overline{g} and $\iota : M \rightarrow \mathbb{R}$ is a differentiable function. If $y \in M$ is the solution of the constrained extremum problem $\min_{x \in M} \iota(x)$, then*

- (i) $(\text{grad } \iota)(y) \in T_y^{\perp} M$;
- (ii) the bilinear form $L : T_y M \times T_y M \rightarrow \mathbb{R}$;

$$L(X, Y) = \overline{g}(\varsigma(X, Y), (\text{grad } \iota)(y)) + \mathcal{H}ess_{\iota}(X, Y)$$

is positive semi-definite, where ς is the second fundamental form of M in \overline{M} .

4. Main result 1

Theorem 4.1. *Let M be an m -dimensional totally real submanifold in an n -dimensional $(LCS)_n$ -manifold \overline{M} . Then*

- (i) *The normalized δ -Casorati curvature $\delta_{\mathcal{C}}(m-1)$ satisfies*

$$\varrho \leq \delta_{\mathcal{C}}(m-1) - \frac{\alpha^2 - \rho}{m}.$$

Furthermore, the equality sign holds if and only if M is an invariantly quasi-umbilical submanifold with trivial normal connection in $\overline{M}(c)$, such that with respect to orthonormal frames of $T_{\varphi}M$ and $T_{\varphi}^{\perp}M$, respectively, the shape operators $\mathcal{S}_a \equiv \mathcal{S}_{\mathcal{E}_a}$, $a \in \{m+1, \dots, n\}$, are of the following form

$$(21) \quad \mathcal{S}_{m+1} = \begin{pmatrix} \beta & \dots & 0 & 0 \\ 0 & \dots & 0 & 0 \\ 0 & \dots & 0 & 0 \\ \vdots & \ddots & \vdots & \vdots \\ 0 & \dots & \beta & 0 \\ 0 & \dots & 0 & 2\beta \end{pmatrix}, \quad \mathcal{S}_{m+2} = \dots = \mathcal{S}_n = 0.$$

- (ii) *The normalized δ -Casorati curvature $\widehat{\delta}_{\mathcal{C}}(m-1)$ satisfies*

$$\varrho \leq \widehat{\delta}_{\mathcal{C}}(m-1) - \frac{\alpha^2 - \rho}{m}.$$

Furthermore, the equality sign holds if and only if M is an invariantly quasi-umbilical submanifold with trivial normal connection in $\overline{M}(c)$, such that with respect to orthonormal frames of $T_{\varphi}M$ and $T_{\varphi}^{\perp}M$, respectively, the shape operators $\mathcal{S}_a \equiv \mathcal{S}_{\mathcal{E}_a}$, $a \in \{m+1, \dots, n\}$, are of the following form

$$(22) \quad \mathcal{S}_{m+1} = \begin{pmatrix} 2\beta & \dots & 0 & 0 \\ 0 & \dots & 0 & 0 \\ 0 & \dots & 0 & 0 \\ \vdots & \ddots & \vdots & \vdots \\ 0 & \dots & 2\beta & 0 \\ 0 & \dots & 0 & \beta \end{pmatrix}, \quad \mathcal{S}_{m+2} = \dots = \mathcal{S}_n = 0.$$

Proof. Let $\{\mathcal{E}_1, \dots, \mathcal{E}_m\}$ be an orthonormal frame of $T_{\varphi}M$ and $\{\mathcal{E}_{m+1}, \dots, \mathcal{E}_n\}$ be an orthonormal frame of $T_{\varphi}^{\perp}M$, $\varphi \in M$. From [10], we get

$$2\sigma = -(m-1)(\alpha^2 - \rho) + m^2\|\mathcal{H}\|^2 - m\mathcal{C}.$$

Let us take a quadratic polynomial \mathbb{K} in the components of the second fundamental form

$$(23) \quad \mathbb{K} = \frac{m(m-1)}{2}\mathcal{C} + \frac{m^2-1}{2}\mathcal{C}(\Psi) + 2\sigma - (m-1)(\alpha^2 - \rho).$$

Without loss of generality, we assume that Ψ is spanned by $\mathcal{E}_1, \dots, \mathcal{E}_{m-1}$ and together (23), we find that

$$(24) \quad \mathbb{K} = \frac{m+1}{2} \sum_{a=m+1}^n \left[\sum_{i,j=1}^m (\zeta_{ij}^a)^2 + \sum_{i,j=1}^{m-1} (\zeta_{ij}^a)^2 \right] - \sum_{a=m+1}^n \left[\sum_{i=1}^m \zeta_{ii}^a \right]^2.$$

Also,

$$(25) \quad \begin{aligned} \mathbb{K} &= \sum_{a=m+1}^n \sum_{i=1}^{m-1} \left[m(\zeta_{ii}^a)^2 + (m+1)(\zeta_{im}^a)^2 \right] \\ &+ \sum_{a=m+1}^n \left[2(m+1) \sum_{1 \leq i < j \leq m-1} (\zeta_{ij}^a)^2 - 2 \sum_{1 \leq i < j \leq m} \zeta_{ii}^a \zeta_{jj}^a + \frac{m-1}{2} (\zeta_{mm}^a)^2 \right] \\ &\geq \sum_{a=m+1}^n \sum_{i=1}^{m-1} m(\zeta_{ii}^a)^2 + \sum_{a=m+1}^n \left[-2 \sum_{1 \leq i < j \leq m} \zeta_{ii}^a \zeta_{jj}^a + \frac{m-1}{2} (\zeta_{mm}^a)^2 \right]. \end{aligned}$$

For $a = m+1, \dots, n$, we suppose the following quadratic form $f_a : \mathbb{R}^m \rightarrow \mathbb{R}$,

$$(26) \quad f_a(\zeta_{11}^a, \dots, \zeta_{mm}^a) = \sum_{i=1}^{m-1} m(\zeta_{ii}^a)^2 - 2 \sum_{1 \leq i < j \leq m} \zeta_{ii}^a \zeta_{jj}^a + \frac{m-1}{2} (\zeta_{mm}^a)^2$$

and the constrained extremum problem $\min f_a$ subject to the component of trace \mathcal{H} ,

$$\varphi : \zeta_{11}^a + \dots + \zeta_{mm}^a = \gamma^a,$$

where γ^a is a real constant.

The function f_a has the following partial derivatives:

$$(27) \quad \begin{aligned} \frac{\partial f_a}{\partial \zeta_{11}^a} &= 2m\zeta_{11}^a - 2 \sum_{i=2}^m \zeta_{ii}^a, \\ \frac{\partial f_a}{\partial \zeta_{22}^a} &= 2m\zeta_{22}^a - 2\zeta_{11}^a - 2 \sum_{i=3}^m \zeta_{ii}^a, \\ &\vdots \\ \frac{\partial f_a}{\partial \zeta_{m-1 \ m-1}^a} &= 2m\zeta_{m-1 \ m-1}^a - 2 \sum_{i=1}^{m-2} \zeta_{ii}^a - 2\zeta_{mm}^a, \\ \frac{\partial f_a}{\partial \zeta_{mm}^a} &= -2 \sum_{i=1}^{m-1} \zeta_{ii}^a + (m-1)\zeta_{mm}^a. \end{aligned}$$

For an optimal solution $(\zeta_{11}^a, \dots, \zeta_{mm}^a)$ of the problem in question, the vector $\text{grad } f_a$ is normal at φ . From (27), we have a following critical point of the considered problem:

$$(28) \quad \zeta_{11}^a = \zeta_{22}^a = \dots = \zeta_{m-1 \ m-1}^a = \frac{\gamma^a}{m+1}, \quad \zeta_{mm}^a = \frac{2\gamma^a}{m+1}.$$

Now, we use Lemma 3.1 and for this, we fix an arbitrary point $y \in \varphi$. The bilinear form

$$\mathbb{L} : T_y \varphi \times T_y \varphi \rightarrow \mathbb{R}$$

is defined by

$$\mathbb{L}(X, Y) = \langle \tilde{h}(X, Y), (\text{grad } f_a)(y) \rangle + \mathcal{H}ess_{f_a}(X, Y),$$

where \tilde{h} denotes the second fundamental form of φ in \mathbb{R}^m and $\langle \cdot, \cdot \rangle$ denotes the standard inner product on \mathbb{R}^m . So, we have the following:

$$\begin{aligned} \mathbb{L}(Z, Z) &= -2(Z_1, \dots, Z_{m-1}, Z_m) \\ &= \begin{pmatrix} -m & 1 & 1 & \dots & 1 & 1 \\ 1 & -m & 1 & \dots & 1 & 1 \\ 1 & 1 & -m & \dots & 1 & 1 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 1 & 1 & 1 & \dots & -m & 1 \\ 1 & 1 & 1 & \dots & 1 & \frac{1-m}{2} \end{pmatrix} \begin{pmatrix} Z_1 \\ Z_2 \\ \vdots \\ \vdots \\ Z_{m-1} \\ Z_m \end{pmatrix} \\ &= 2(m+1) \sum_{i=1}^{m-1} Z_i^2 + (m+1)Z_m^2 - 2(Z_1 + \dots + Z_m)^2 \\ &= 2(m+1) \sum_{i=1}^{m-1} Z_i^2 + (m+1)Z_m^2 \\ &\geq 0, \end{aligned}$$

where we have used the relation $\sum_{i=1}^m Z_i^2 = 0$ (because a vector Z is tangent to φ at $y \in \varphi$ and φ is totally geodesic in \mathbb{R}^m). Thus, the point $(\zeta_{11}^a, \dots, \zeta_{mm}^a)$ (see (28)) is a global minimum point. From relations (25) and (28), we get $\mathbb{K} \geq 0$ and hence we have

$$2\sigma \leq m(m-1)\mathcal{C} + \frac{m^2-1}{2}\mathcal{C}(\Psi) - (m-1)(\alpha^2 - \rho).$$

Further, we find that

$$\varrho \leq \mathcal{C} + \frac{(m+1)}{2m}\mathcal{C}(\Psi) - \frac{\alpha^2 - \rho}{m}.$$

This is the required inequality in (i). The equality in (i) holds if and only if

$$(29) \quad \zeta_{ij}^a = 0, \quad \forall i, j \in \{1, \dots, m\}, \quad i \neq j, \quad a \in \{m+1, \dots, n\}$$

and

$$(30) \quad \zeta_{mm}^a = 2\zeta_{11}^a = \dots = 2\zeta_{m-1, m-1}^a \quad \forall a \in \{m+1, \dots, n\}.$$

With the help of (29) and (30), we find that the submanifold is invariantly quasi-umbilical and the shape operators are given by (21).

Similarly, one can easily prove the geometric inequality (ii). \square

Corollary 4.2. *Let M be an m -dimensional C -totally real submanifold in an n -dimensional $(LCS)_n$ -manifold \bar{M} . Then:*

- (i)
- The normalized δ -Casorati curvature $\delta_{\mathcal{C}}(m-1)$ satisfies*

$$\varrho \leq \delta_{\mathcal{C}}(m-1).$$

Furthermore, the equality sign holds if and only if M is an invariantly quasi-umbilical submanifold with trivial normal connection in $\overline{M}(c)$, such that with respect to orthonormal frames of $T_{\wp}M$ and $T_{\wp}^{\perp}M$, respectively, the shape operators $\mathcal{S}_a \equiv \mathcal{S}_{\mathcal{E}_a}$, $a \in \{m+1, \dots, n\}$, is given by (21).

- (ii)
- The normalized δ -Casorati curvature $\widehat{\delta}_{\mathcal{C}}(m-1)$ satisfies*

$$\varrho \leq \widehat{\delta}_{\mathcal{C}}(m-1).$$

Furthermore, the equality sign holds if and only if M is an invariantly quasi-umbilical submanifold with trivial normal connection in $\overline{M}(c)$, such that with respect to orthonormal frames of $T_{\wp}M$ and $T_{\wp}^{\perp}M$, respectively, the shape operators $\mathcal{S}_a \equiv \mathcal{S}_{\mathcal{E}_a}$, $a \in \{m+1, \dots, n\}$, is given by (22).

5. Main result 2

Let $\{\mathcal{E}_1, \dots, \mathcal{E}_n\}$ be an orthonormal basis of the tangent space \overline{M} and \mathcal{N} be a unit tangent vector at $\wp \in \overline{M}^n$ such that $\mathcal{E}_1 = \mathcal{N}$ refracting to M^m , $\{\mathcal{E}_1, \dots, \mathcal{E}_m\}$ is the orthonormal basis to the tangent space $T_{\wp}M$ with respect to induced quarter symmetric metric connection. Let us denote the scalar curvature and normalized scalar curvature of M with respect to induced connection associated to the quarter symmetric metric connection by $\hat{\sigma}(\wp)$ at \wp and $\hat{\varrho}$, respectively. Then we prove the following:

Theorem 5.1. *Let M be an m -dimensional totally real submanifold in an n -dimensional $(LCS)_n$ -manifold \overline{M} with respect to quarter symmetric metric connection. Then*

- (i)
- The normalized δ -Casorati curvature $\delta_{\mathcal{C}}(m-1)$ satisfies*

$$\hat{\varrho} \leq \delta_{\mathcal{C}}(m-1) - \frac{(2m-1)\alpha}{m(m-1)} - \frac{\alpha\eta^2(\mathcal{N})}{m-1}.$$

Furthermore, the equality sign holds if and only if M is an invariantly quasi-umbilical submanifold with trivial normal connection in $\overline{M}(c)$, such that with respect to orthonormal frames of $T_{\wp}M$ and $T_{\wp}^{\perp}M$, respectively, the shape operators $\mathcal{S}_a \equiv \mathcal{S}_{\mathcal{E}_a}$, $a \in \{m+1, \dots, n\}$, is given by (21).

- (ii)
- The normalized δ -Casorati curvature $\widehat{\delta}_{\mathcal{C}}(m-1)$ satisfies*

$$\hat{\varrho} \leq \widehat{\delta}_{\mathcal{C}}(m-1) - \frac{(2m-1)\alpha}{m(m-1)} - \frac{\alpha\eta^2(\mathcal{N})}{m-1}.$$

Furthermore, the equality sign holds if and only if M is an invariantly quasi-umbilical submanifold with trivial normal connection in $\overline{M}(c)$,

such that with respect to orthonormal frames of $T_\varphi M$ and $T_\varphi^\perp M$, respectively, the shape operators $\mathcal{S}_a \equiv \mathcal{S}_{\mathcal{E}_a}$, $a \in \{m+1, \dots, n\}$, is given by (22).

Proof. Following [10], we have

$$(31) \quad 2\hat{\sigma} = -(2m-1)\alpha - m\alpha\eta^2(\mathcal{N}) + m^2\|\mathcal{H}\|^2 - \|\zeta\|^2.$$

Again by using T. Oprea's optimization technique, one can prove the theorem. \square

Note that the scalar curvature and hence the normalized scalar curvature of C -totally real submanifold of a $(LCS)_n$ -manifold with respect to induced Levi-Civita connection and induced quarter symmetric metric connection are identical (see [10]). Thus, we have the following:

Corollary 5.2. *Let M be an m -dimensional C -totally real submanifold in an n -dimensional $(LCS)_n$ -manifold \overline{M} with respect to quarter symmetric metric connection. Then*

- (i) *The normalized δ -Casorati curvature $\delta_C(m-1)$ satisfies*

$$\hat{\rho} \leq \delta_C(m-1).$$

Furthermore, the equality sign holds if and only if M is an invariantly quasi-umbilical submanifold with trivial normal connection in $\overline{M}(c)$, such that with respect to orthonormal frames of $T_\varphi M$ and $T_\varphi^\perp M$, respectively, the shape operators $\mathcal{S}_a \equiv \mathcal{S}_{\mathcal{E}_a}$, $a \in \{m+1, \dots, n\}$, is given by (21).

- (ii) *The normalized δ -Casorati curvature $\hat{\delta}_C(m-1)$ satisfies*

$$\hat{\rho} \leq \hat{\delta}_C(m-1).$$

Furthermore, the equality sign holds if and only if M is an invariantly quasi-umbilical submanifold with trivial normal connection in $\overline{M}(c)$, such that with respect to orthonormal frames of $T_\varphi M$ and $T_\varphi^\perp M$, respectively, the shape operators $\mathcal{S}_a \equiv \mathcal{S}_{\mathcal{E}_a}$, $a \in \{m+1, \dots, n\}$, is given by (22).

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MOHAMMAD HASAN SHAHID
DEPARTMENT OF MATHEMATICS
FACULTY OF NATURAL SCIENCES
JAMIA MILLIA ISLAMIA
NEW DELHI-110025, INDIA
Email address: hasan_jmi@yahoo.com

ALIYA NAAZ SIDDIQUI
DEPARTMENT OF MATHEMATICS
FACULTY OF NATURAL SCIENCES
JAMIA MILLIA ISLAMIA
NEW DELHI-110025, INDIA
Email address: aliyanaazsiddiqui9@gmail.com